

Automated and data- driven chemistry

LECTURE 7 :
Interfacing Equipment
Theoretical Introduction

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01

Signal Types & Transmissions

02

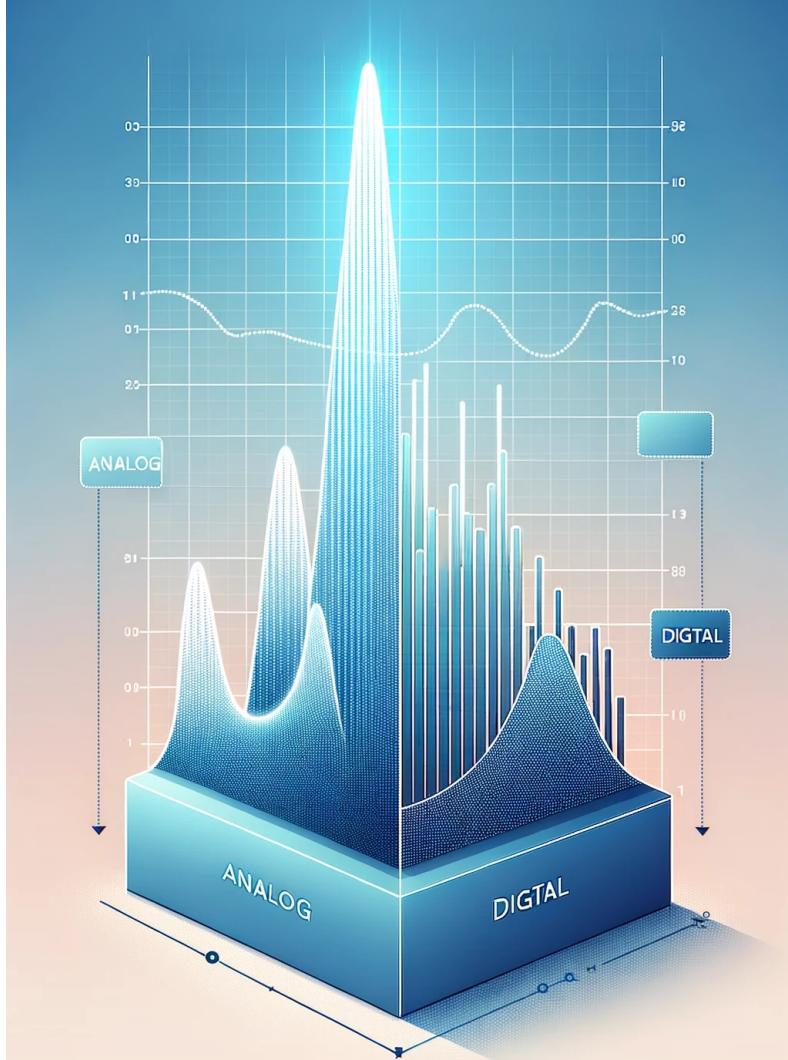
Communication Tools

03

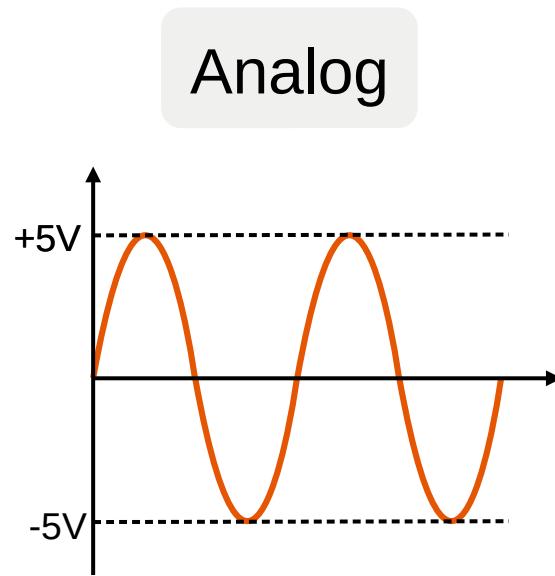
Interfacing Devices

04

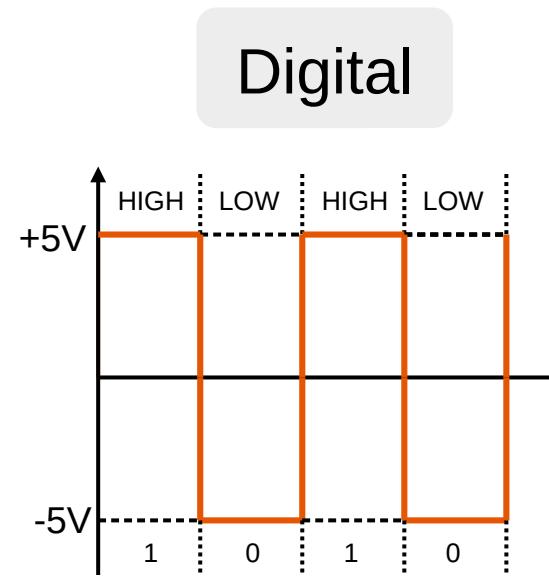
API



1. Signal Types & Transmissions

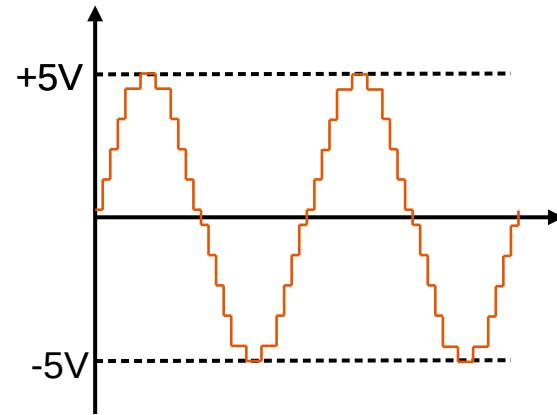


Continuous signal



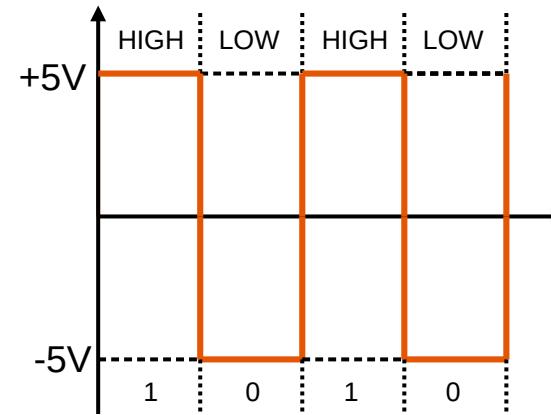
Discrete signal

Digitalized Analog



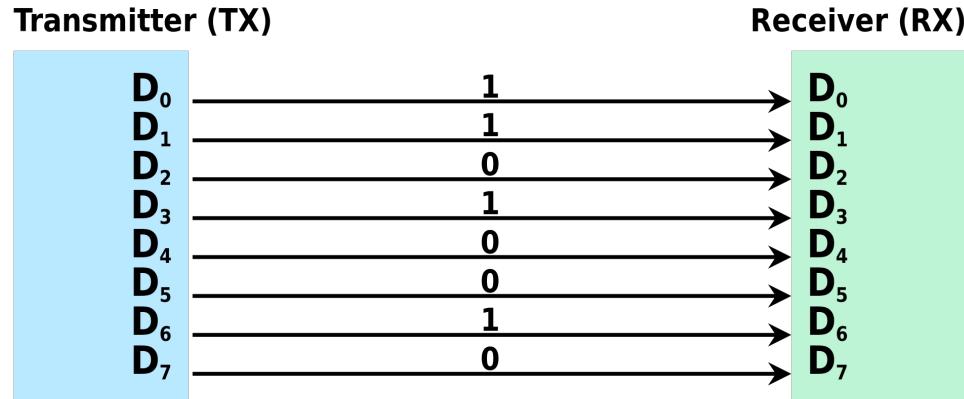
Discrete signal

Digital

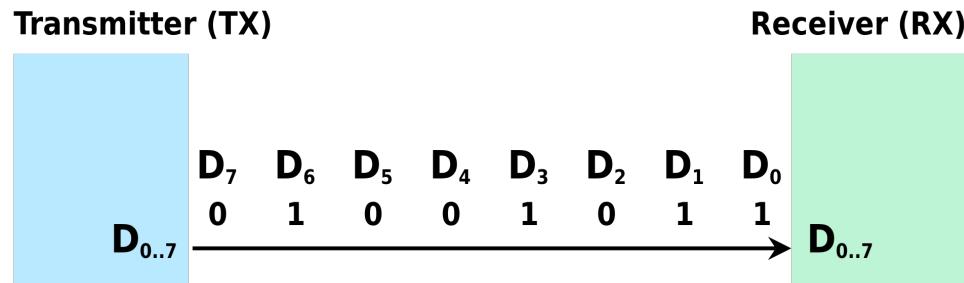


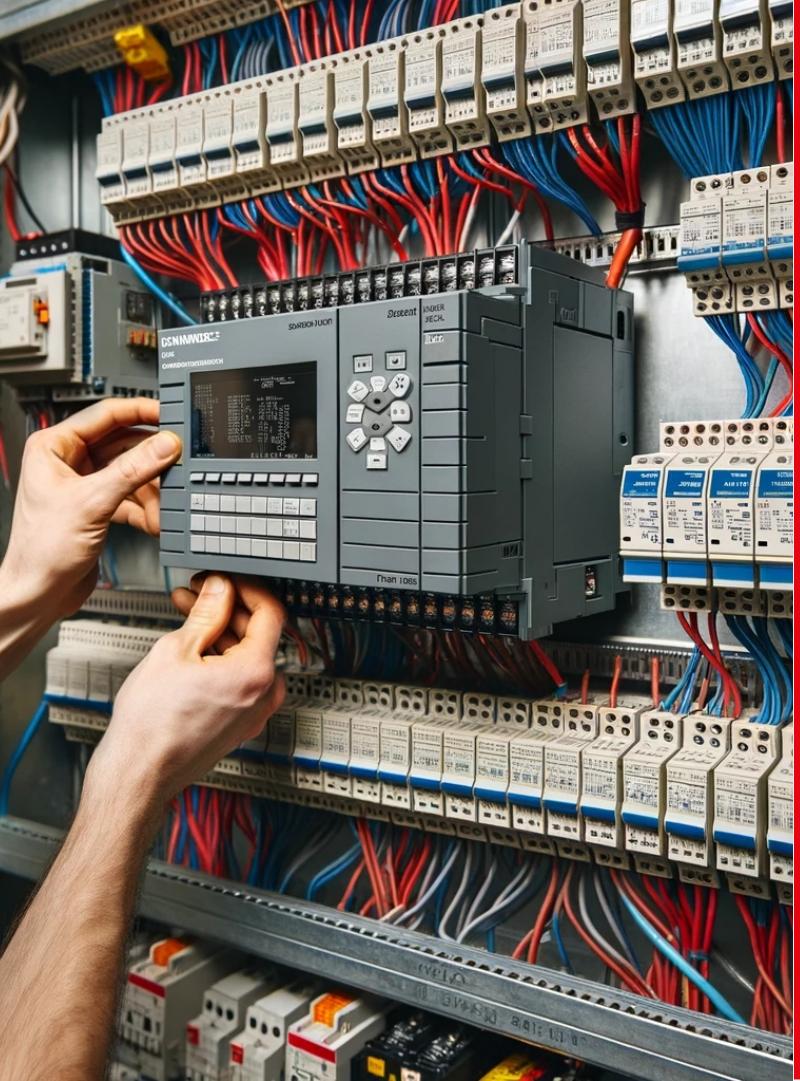
Discrete signal

Parallel interface example



Serial interface example





2. Communication Tools

- To communicate between each others, devices need communication standards. It is a set of rules and conventions that devices must follow to communicate with each other

Cables

USB

RJ45

HDMI

Protocols

TCP/IP

UART

Bluetooth

USB 



- Universal Serial Bus
- A dozen of type of USB port exists
- Short distance (a few meters)
- 4 wires (9 in newer version)
- Not robust (except rs232 which is old model)
- Transmitter (Tx) and Receiver (Rx)

Vcc Tx Rx GND



Type-A
2.0

RS232





RJ45 (Ethernet)



- Designed for Network communication
- Parallel communication (8 wires)
- Send by packets of data in any order
- Long distance (up to 100 m)
- Widely used in industrial setup (Automation)
- Dozens of protocols (TCP/IP, EtherCAT, ModBUS, Profinet, ...)
- Stable in complex environment
- Safe

Display Port (DP)



- Designed and optimized for Audio and Video signals
- Easily adaptable to each others with adapters

- With the high number of device in the lab, if possible, Remote Access Desktop should be privileged
- Many protocol exists, such as RDP (Windows) or VNC  



HDMI

**C13/C14**

- Max 10A

**C19/C20**

- Max 16A

CEE Industrial

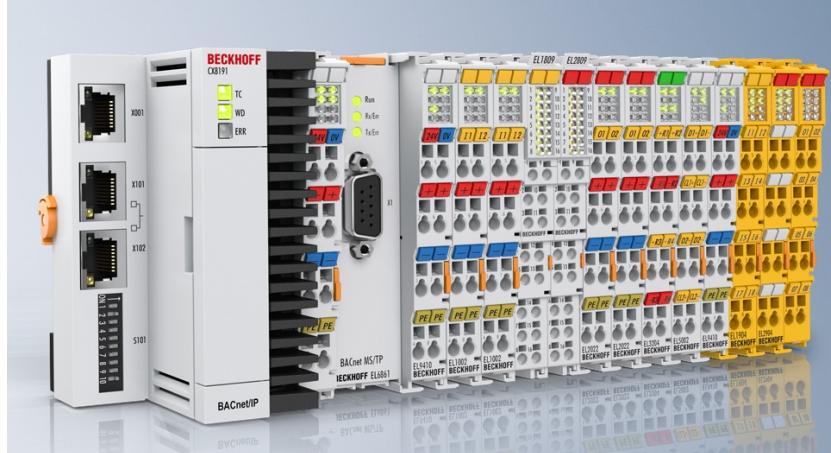
- 200-250V



- 380-480V

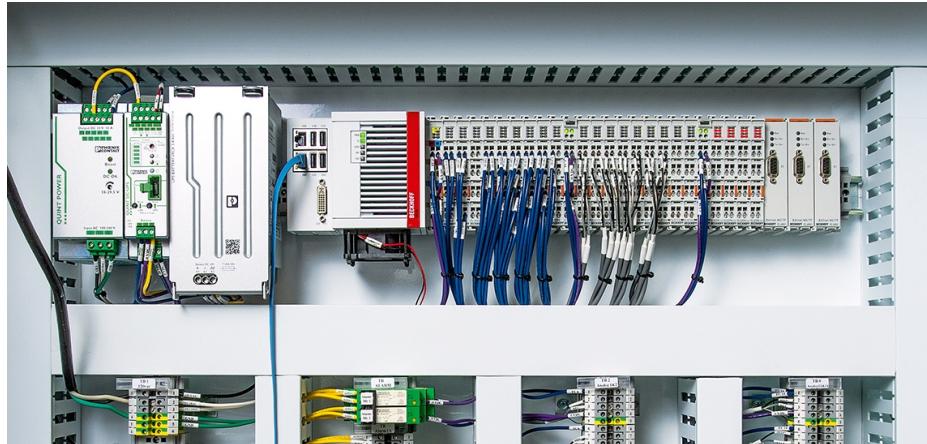


- Max 16A, 32A (and more Amp but rarely used in lab)



- Installed in Electrical Cabinet
- Requires special training
- Lots of norm to respect
- Dangerous to operate when on
- Proprietary software
- Expensive and long delivery time

- Industrial controller
- Safe, durable, works in harsh environment
- Plug & Play connectors
- Allows to easily program and connect tons of sensors and actuators
- Lots of standard communication







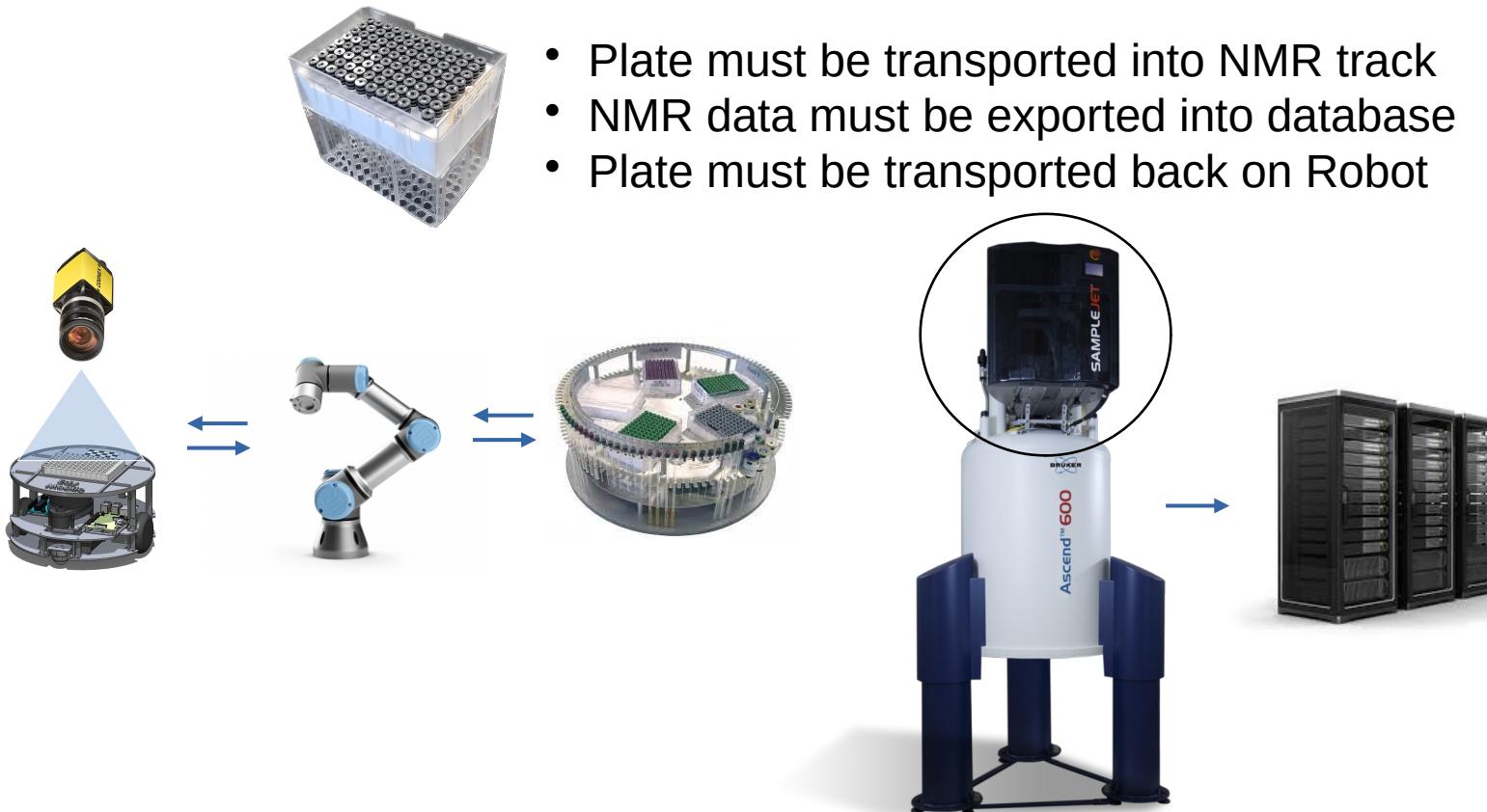


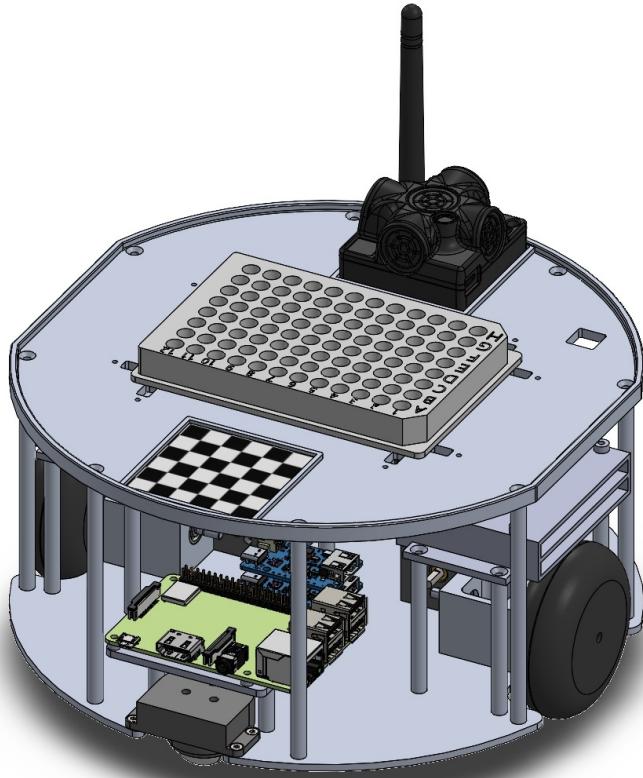


2. Interfacing Devices



EPFL NMR Example





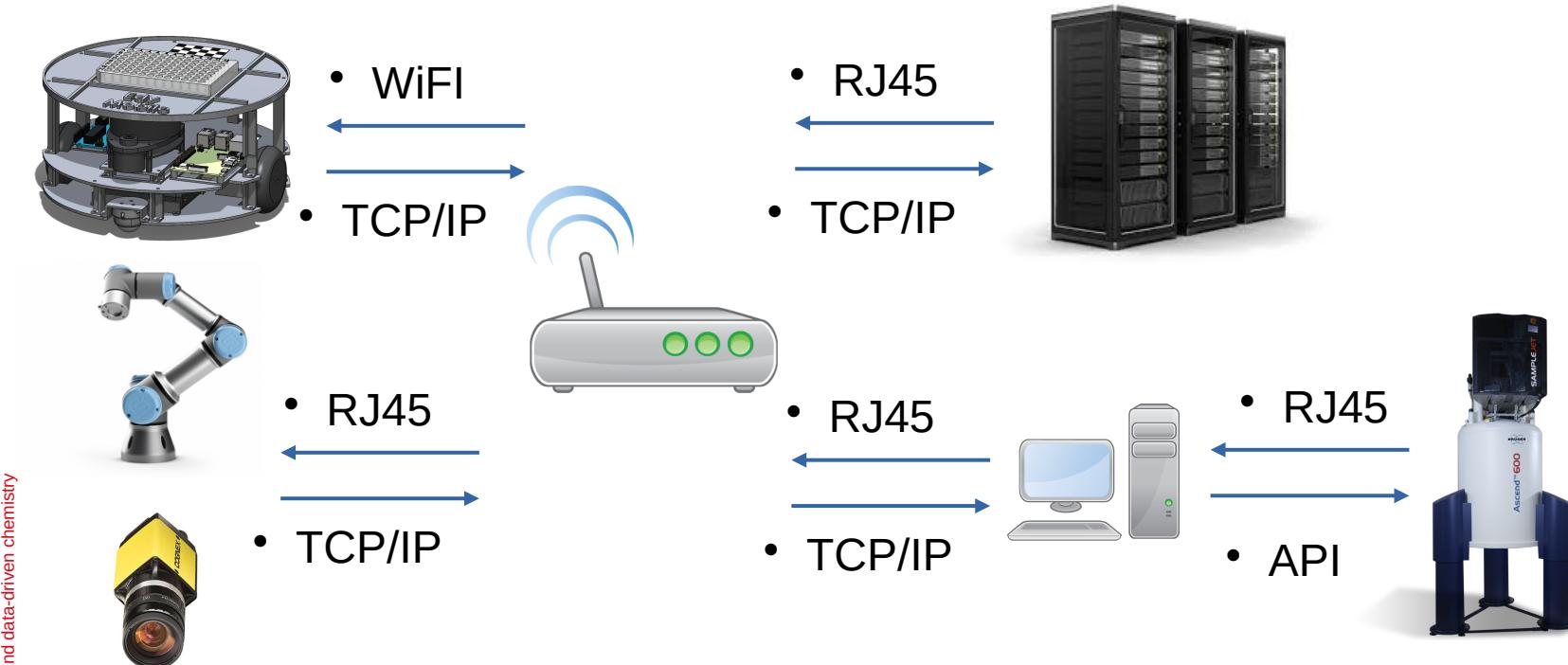
- Onboard PC has WiFi
- Arduino is connected through USB, sending sensors value and receiving motor speed command.
- GPS is connected through USB, sending sensor position



- Controller with Input & Outputs to control Sensors & Actuators (like a PLC)
- Ethernet port with TCP/IP to communicate with it



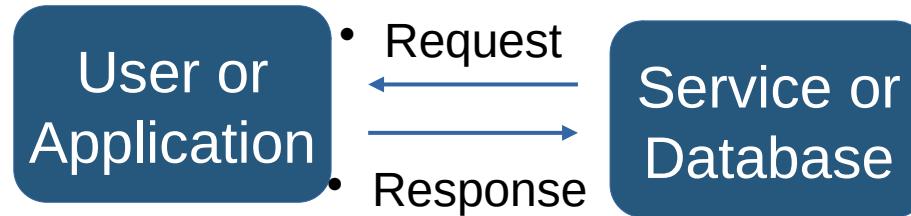
EPFL NMR Example





1. API

API (Application Programming Interface) is a set of rules and protocols that allows different software entities to communicate with each other.



APIs enable seamless integration and data exchange between systems, making them essential for modern software development.

- **Move Rack Holder** : It will move the rack holder to the selected position, allowing the robot to put the rack
- **Measure Sample** : It will charge the sample into the NMR, make the measurement depending on the selected method, uncharge the sample and return the measurement data

Scale API 1.0.0 OAS 3.0

API for managing a scale with tare, weight, door, and temperature functions

default

POST `/scale/tare` Tare the Scale

GET `/scale/weight` Get Weight

POST `/scale/close-door` Close the Door

GET `/scale/temperature` Get Temperature

POST `/scale/stabilize` Stabilize Weight

- Rest API or Soap API for examples are widely used to easily interface two devices in the same network

Thank you for your attention.

Thanks to



Swiss CAT+ team & partners



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Confédération suisse
Confederazione Svizzera
Confederaziun svizra



EPFL



Gimp, Ubuntu Foundation

